



Reproduire les dynamiques territoriales : une manière de mieux les comprendre ?

Arnaud Banos
Géographie-cités

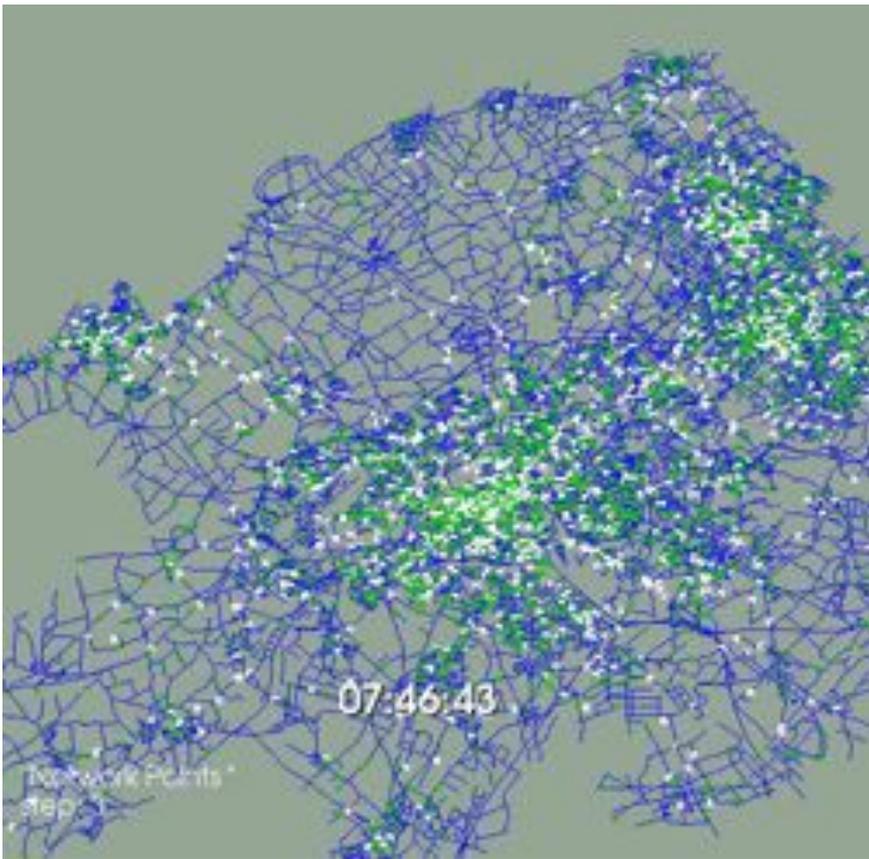
Séminaire PUCA
05 février 2014



Original Artist
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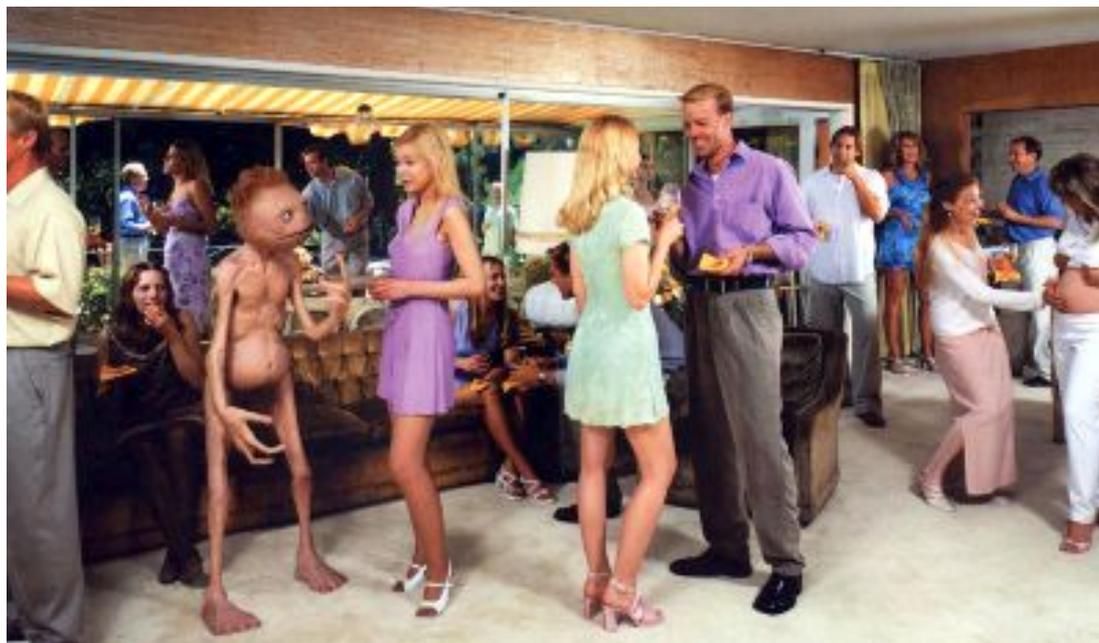
by HAGEN



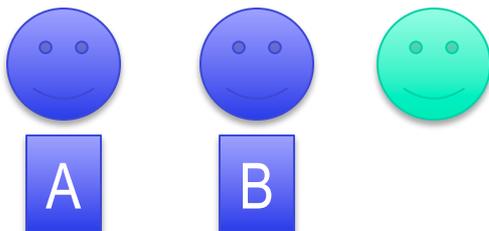




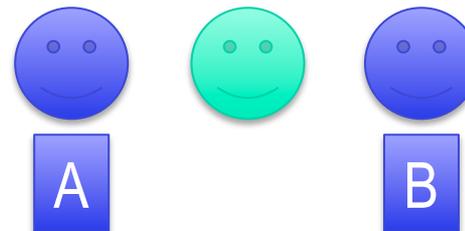
Le jeu de la garden party



Stratégie 1



Stratégie 2



Stratégie 2



A



B



Conclusion

➤ Simuler c'est (aussi) explorer :

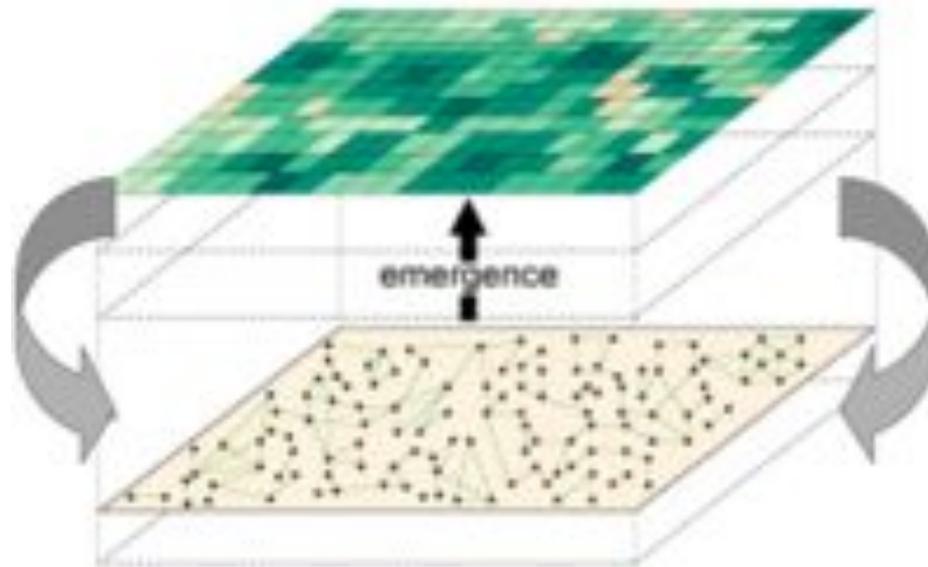
- Micro → macro
- Macro → micro

Expérimentation
in silico



<http://www.jokewala.com/>

Systeme adaptatif complexe



Comportements non coordonnés mais interdépendants
→ Émergence de structures locales

Systeme adaptatif complexe





Modèle de Schelling

	A	B	C	D	E	F	G	H
1	#	#	#	#	○	○	○	
2	#	#	#			○	○	○
3	#	#			○	○	○	
4	#	#	#	○	○	○	○	○
5	#	#	○		○		○	
6	#	○		○				○
7	○		○		○		○	#
8		○				○	#	#

FIGURE 1.5b A highly segregated city.



Move: IF

proportion of « not like me » neighbors > Tolerance

AND

available free place with proportion of NLM neighbors ≤ Tolerance

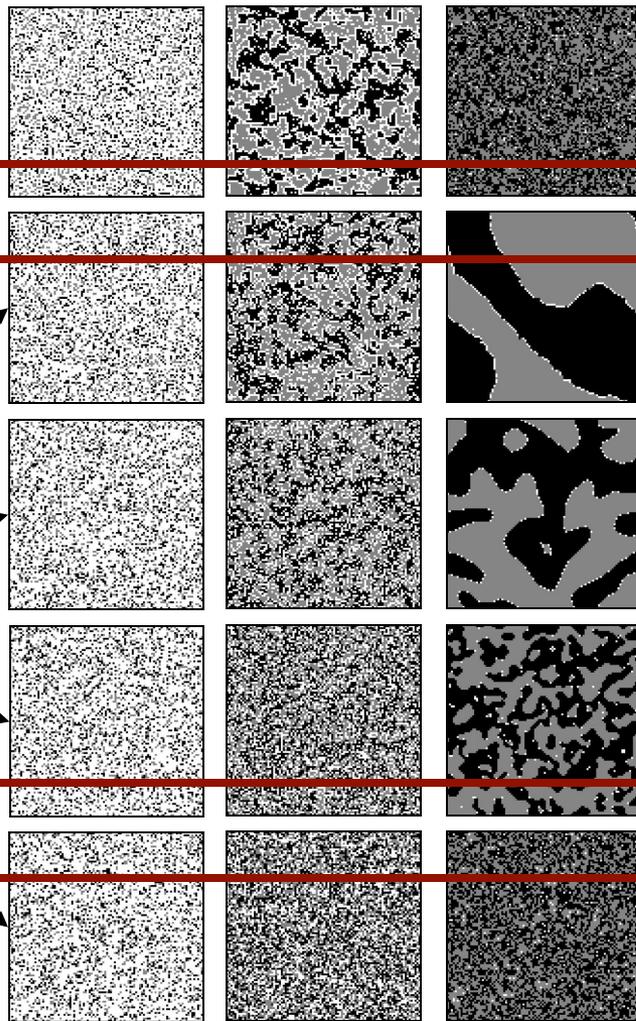
Densités d'agents

« Dynamically frozen state »

(Gauvin, Vannimenus, Nadal, 2009)

Equilibrium

$d = 30\%$ $d = 66\%$ $d = 98\%$



$\lambda = 20\%$

$\lambda = 30\%$

$\lambda = 40\%$

$\lambda = 60\%$

$\lambda = 80\%$



Tolérance

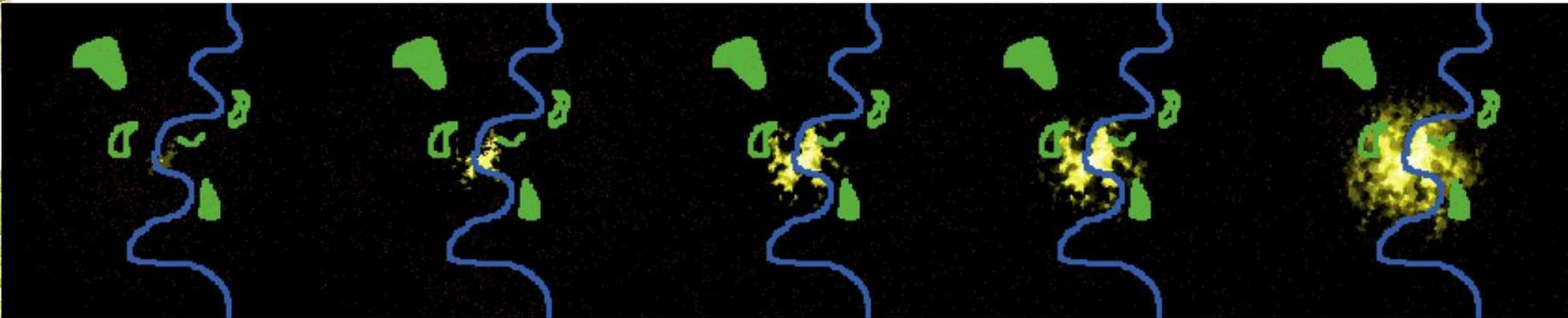


Daudé & Langlois, 2007

Intérêt individuel VS collectif



« if you didn't grow it, you didn't explain it »
(Epstein, Axtell)



<http://arnaudbanos.perso.neuf.fr/home.html>

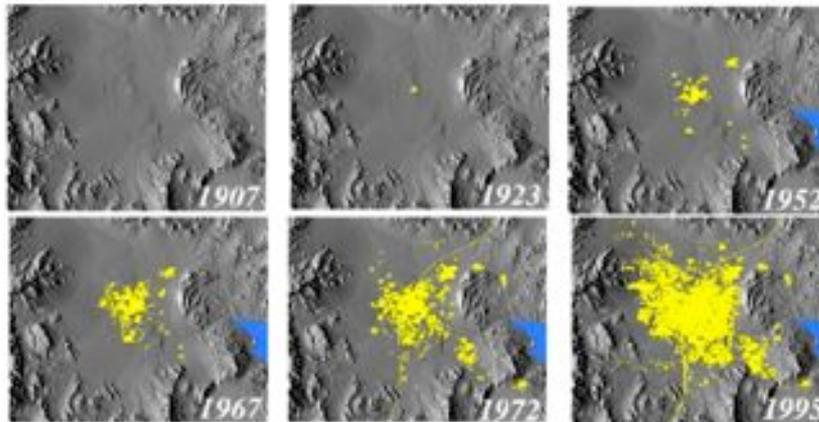
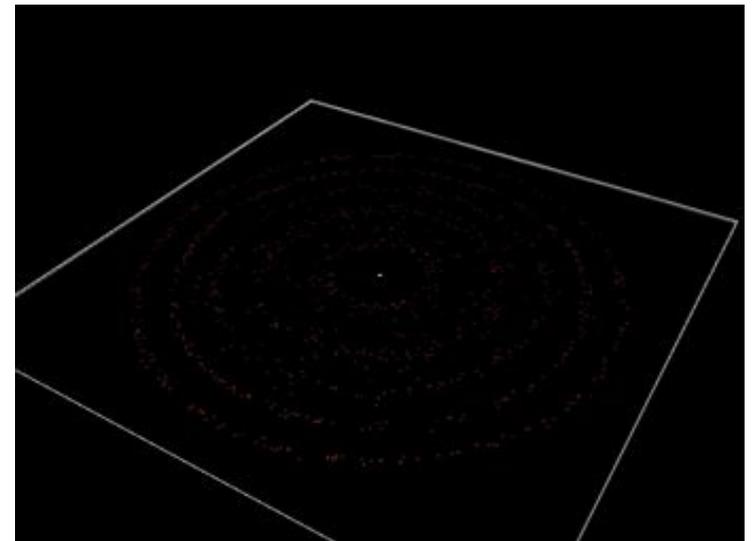


Figure 1: The Growth of Las Vegas from 1907 to 1995
(from Acevedo et al., 1997)



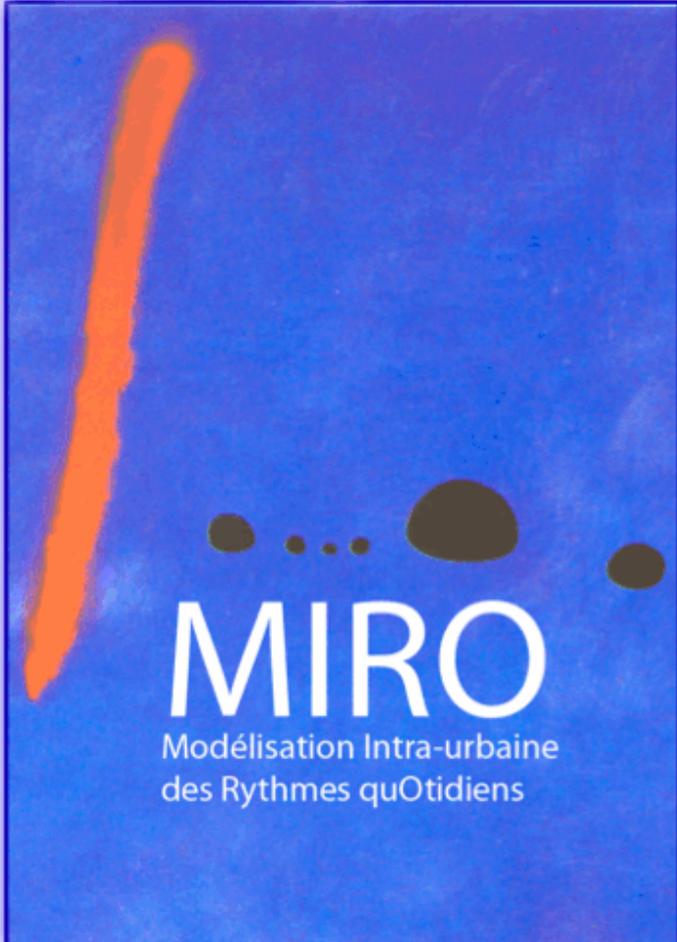
MIRO2

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MIRO
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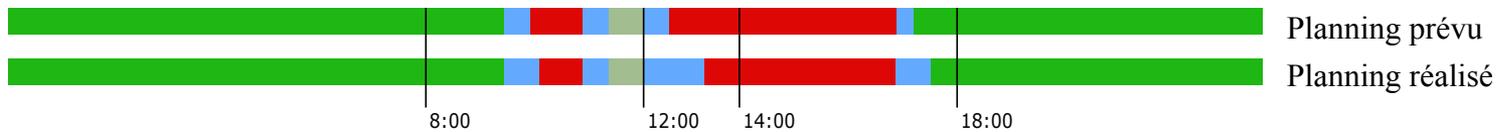
MIRO 2 – GaMiroD

Contact: arnaud.banos@parisgeo.cnrs.fr



Si on laisse trop de liberté aux agents...

➤ Premier jour (temps de transport inconnu)



➤ Deuxième jour (temps de transport connu)

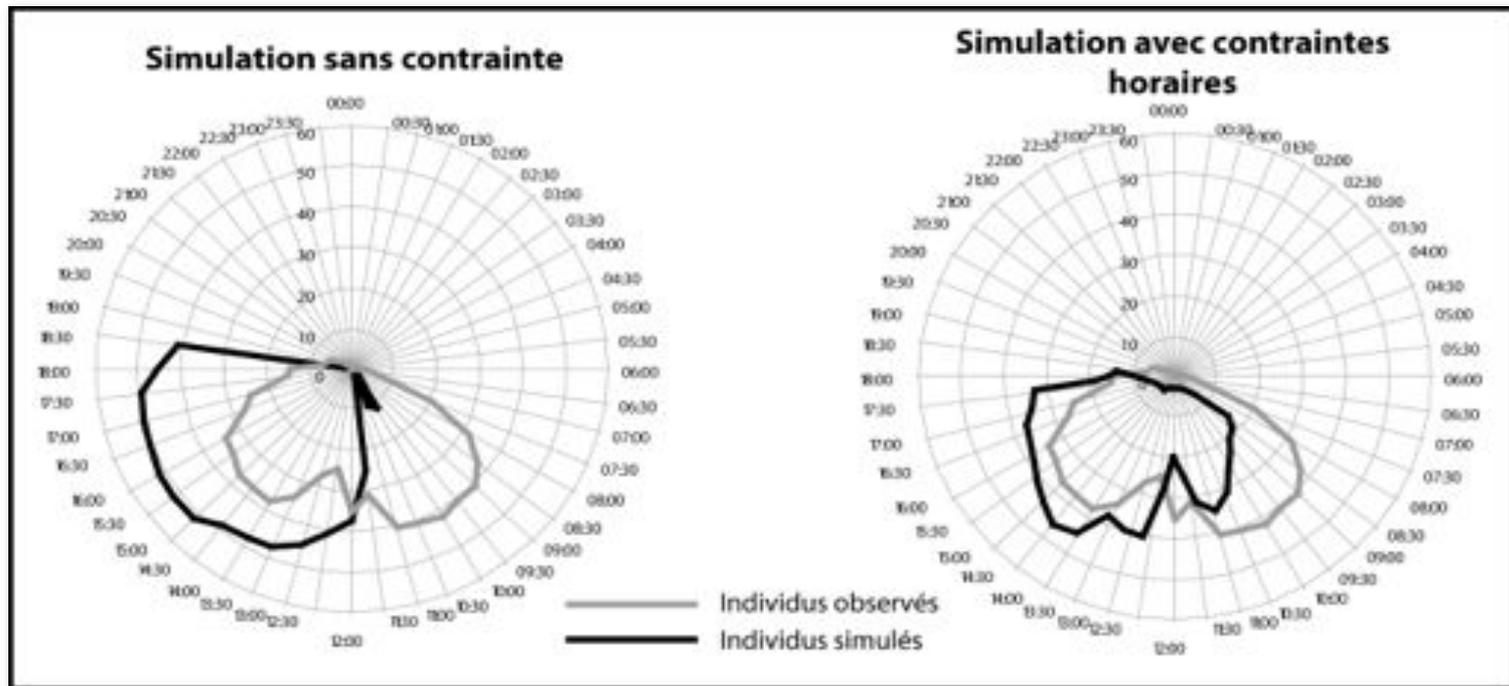


...il faut être prêt à l'assumer !



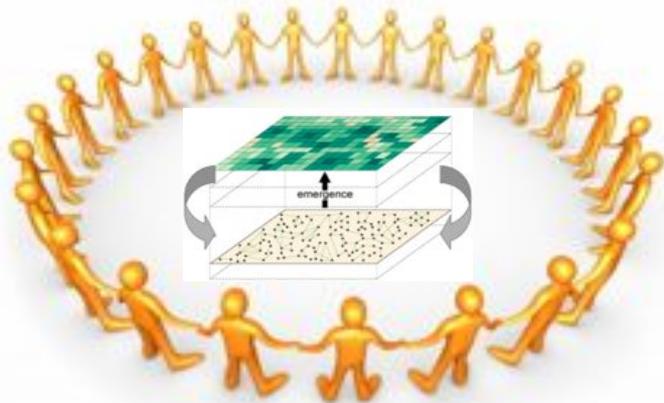


Après tout, pourquoi pas ?





Jouons !



Step 0 - INSTALLATION DES SERVICES

Participants List

Accumulation Graphique Temporelle

Ma Carte de Service Cumulative Temporelle

Control Panel

Interface 2D - Step 000 - State: Running

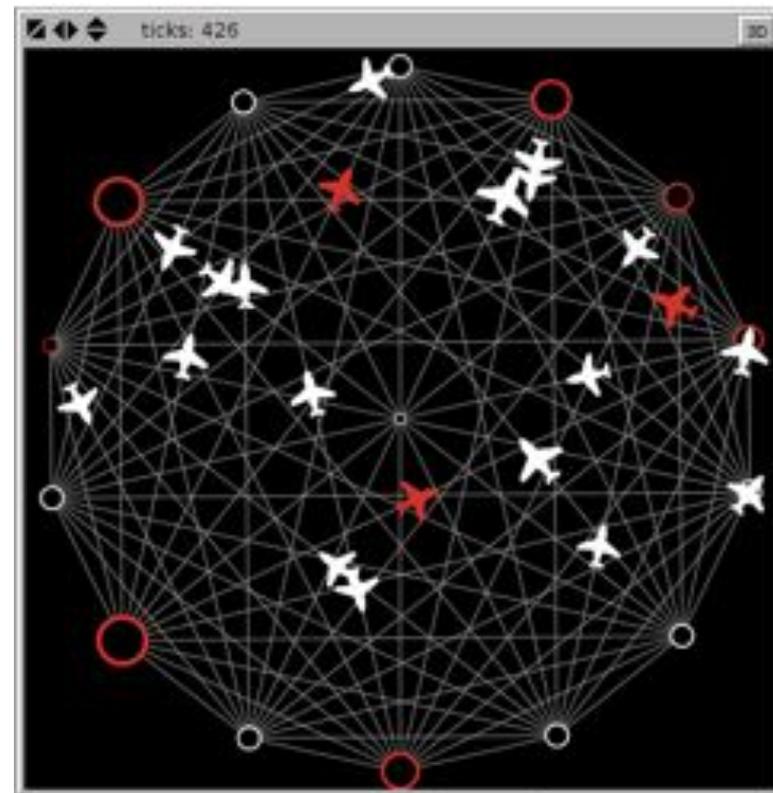
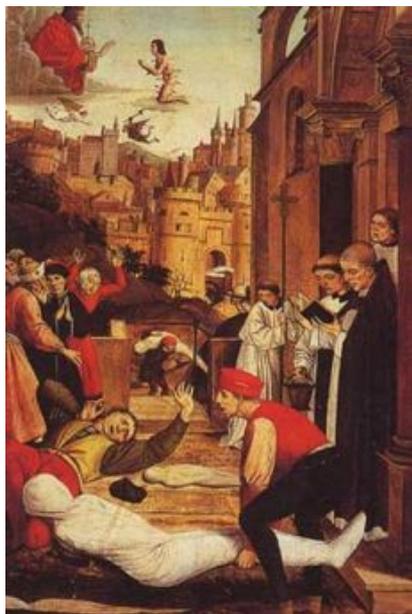
➔ Coopetition



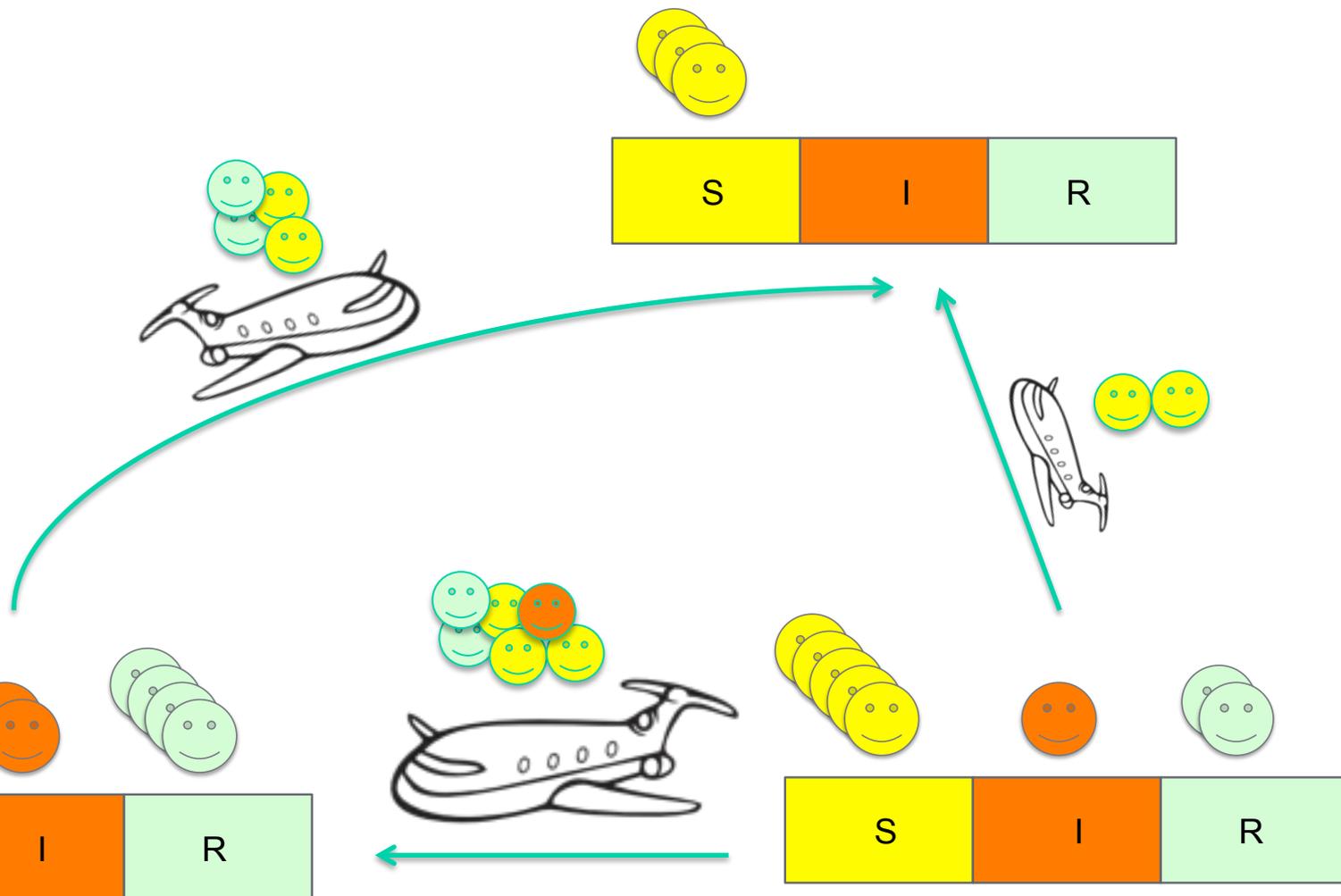
MicMac (PEPS CNRS HuMain 2013-2014)

Banos - Corson – Gaudou – Lapperrière - Rey

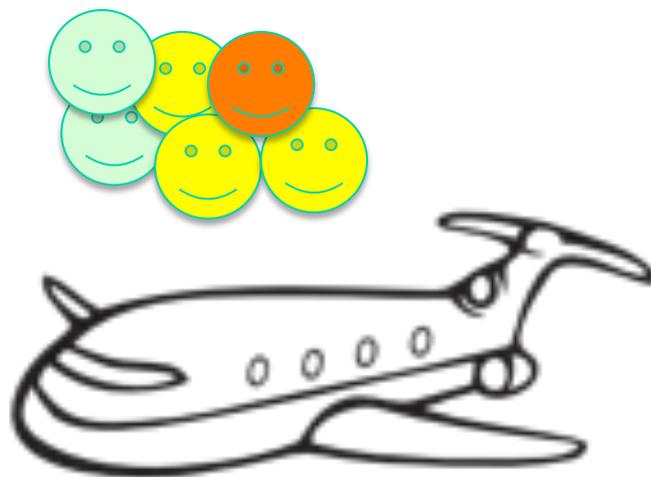
Propagation d'une épidémie dans un réseau



Modèle



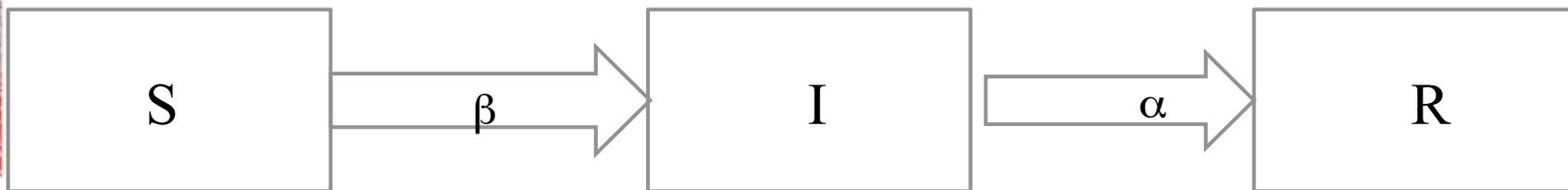
Couplage de systèmes



$$\frac{dS}{dt} = -\beta SI$$

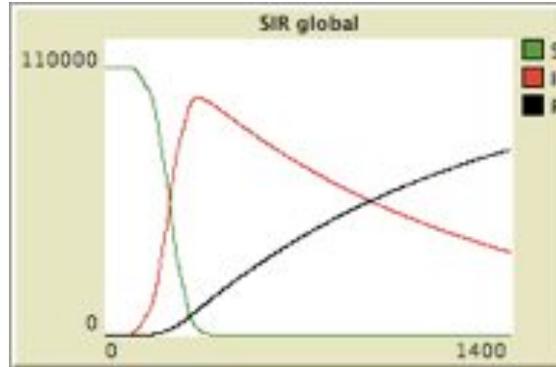
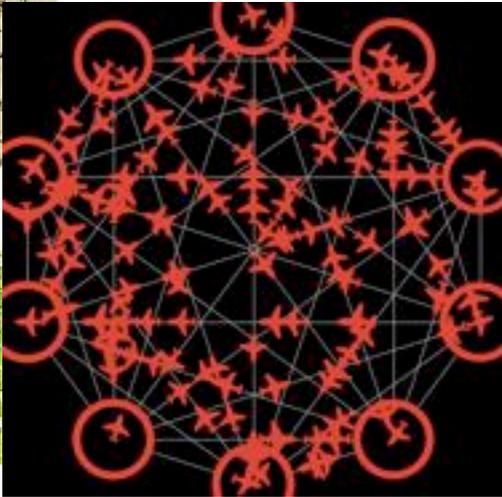
$$\frac{dI}{dt} = \beta SI - \alpha I$$

$$\frac{dR}{dt} = \alpha I$$



Sorties

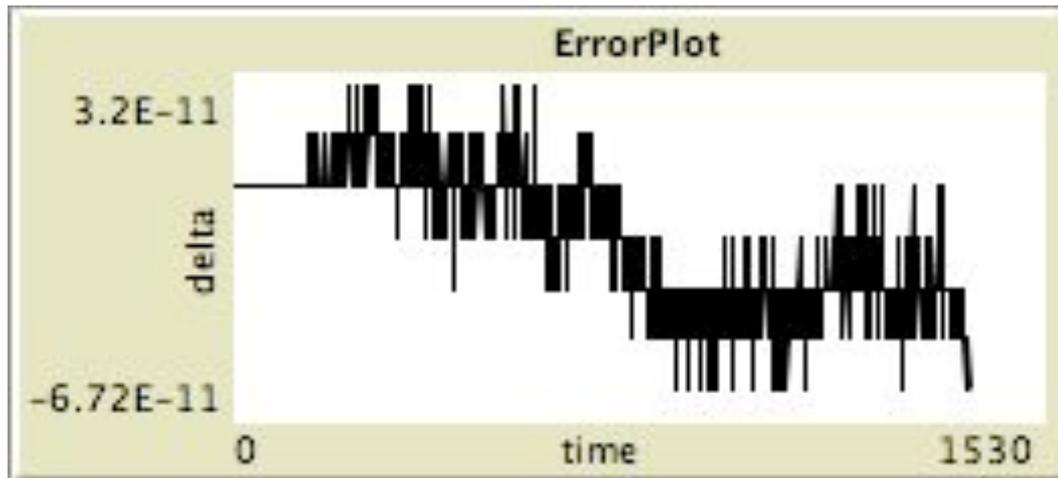
Dynamique globale



Dynamique sur un noeud



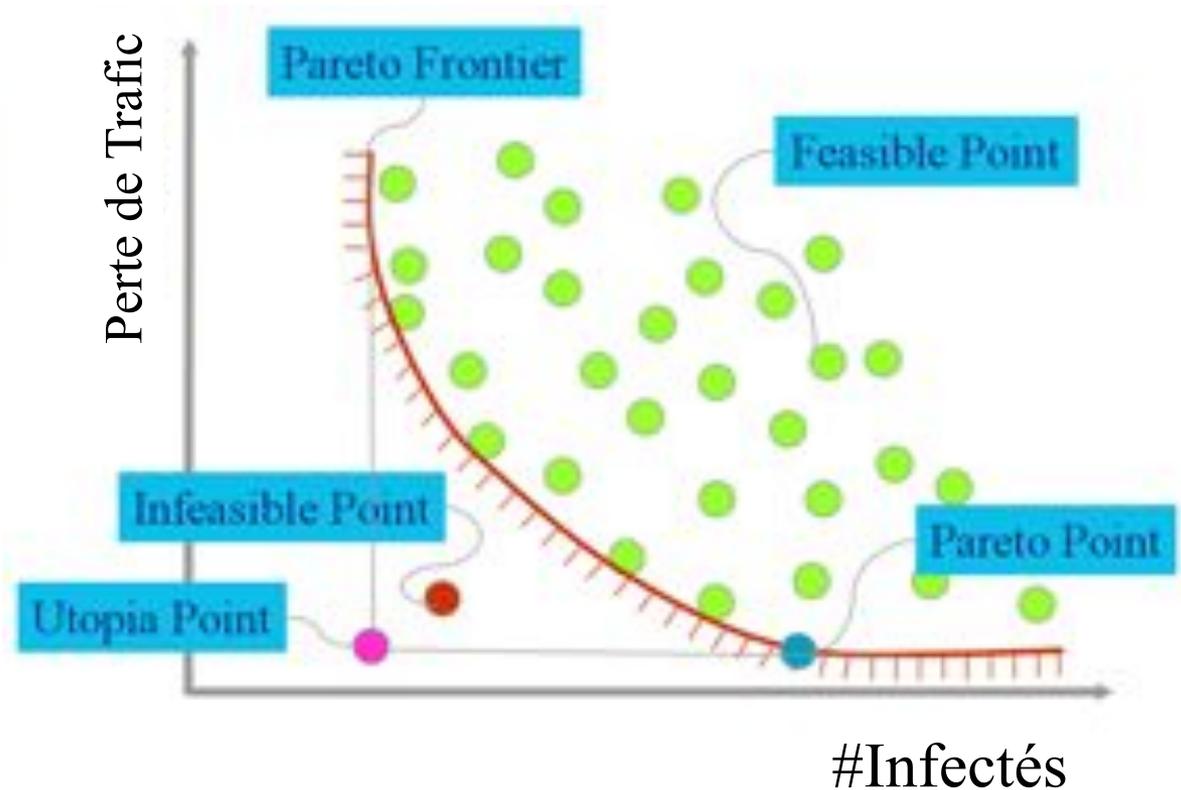
$H^4 = 1.0E-8$



Conservation
de la population

Objectifs

- Minimiser l'épidémie (#Infectés)
- Minimiser la perte de trafic



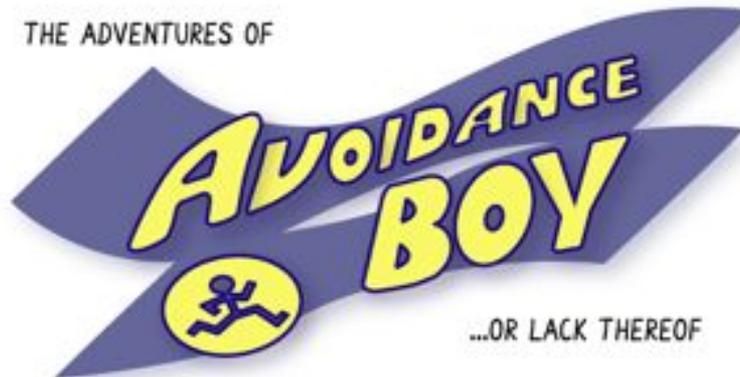
Stratégie 1: quarantaine



Stratégie 2 : évitement



THE ADVENTURES OF



...OR LACK THEREOF

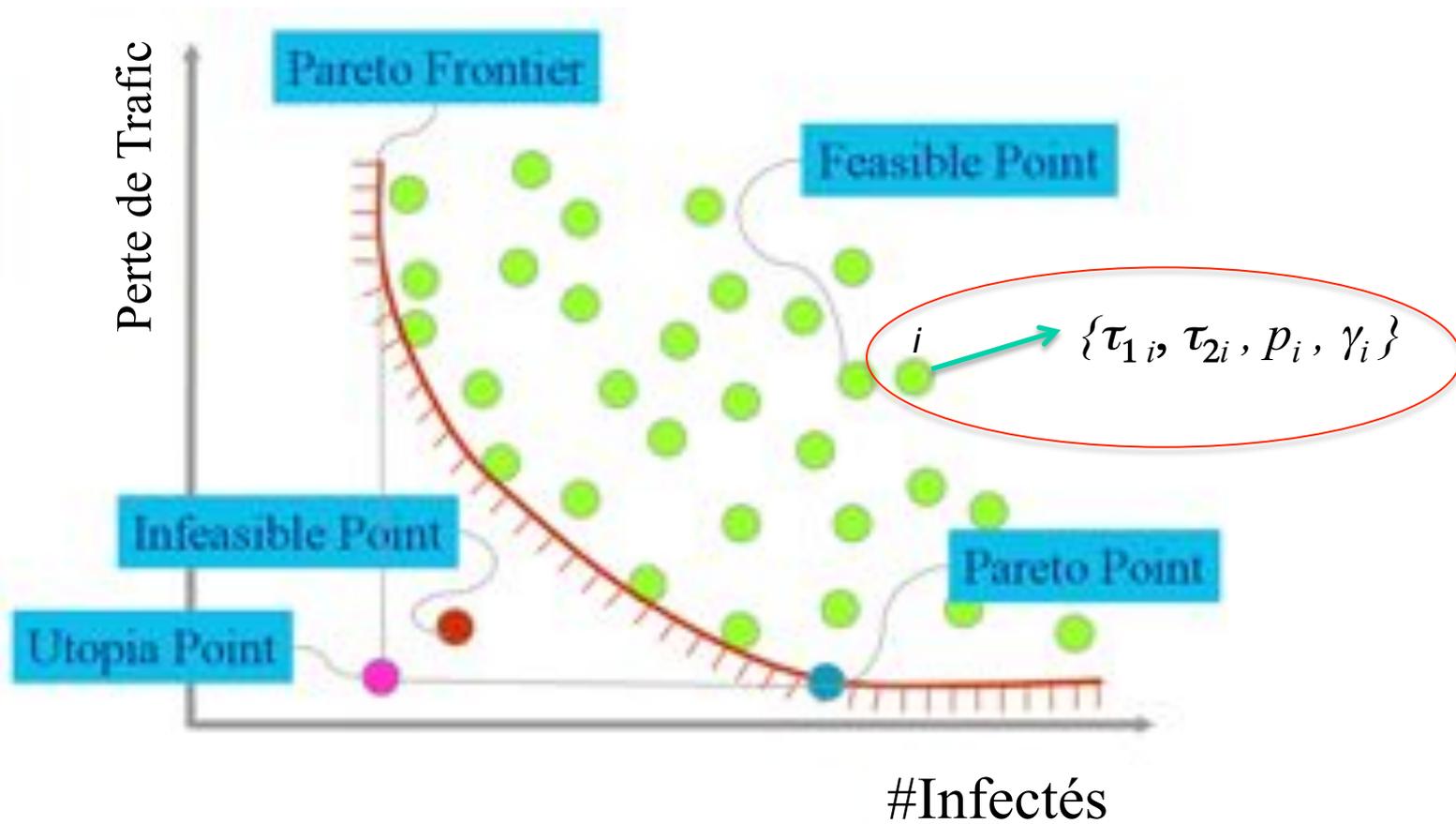
Stratégie 3 : culture du risque



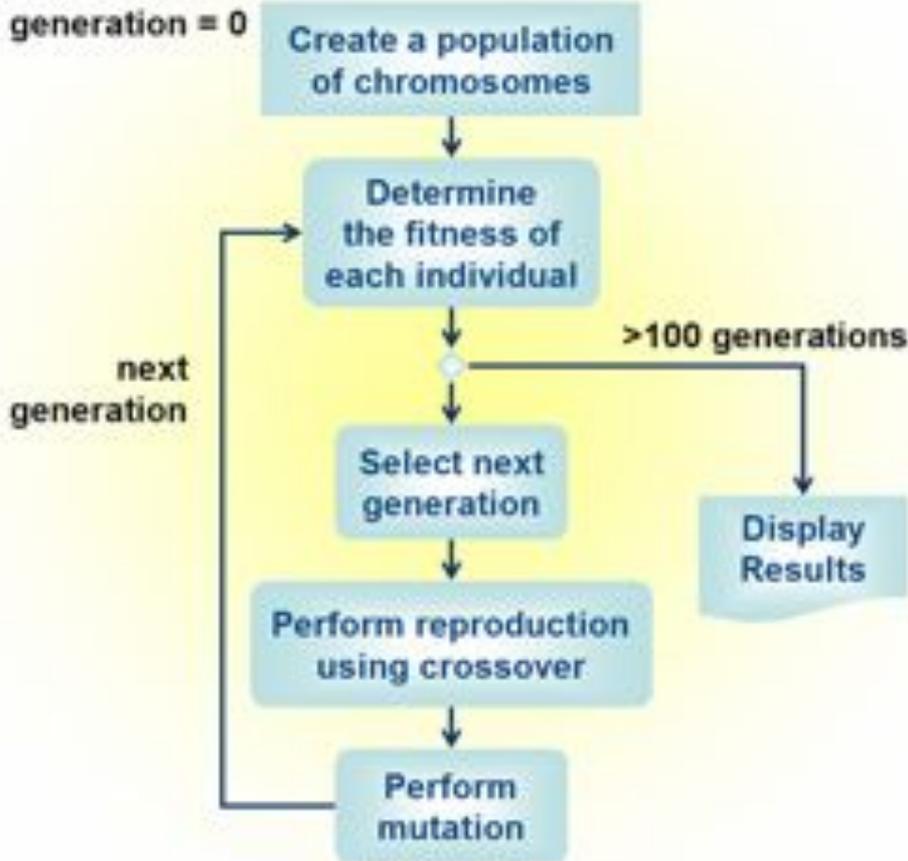
Stratégie 4 : protection



Objectifs



Algorithme génétique



Chromosome = $\{\tau_1, \tau_2, p, \gamma\}$, chaque valeur étant choisie au hasard, $U(0,1)$

